



# The Criminal Brain of AI

Goal Decomposition, Innocent Agents,  
and the Reform of Criminal Law  
in the Age of Algorithmic Autonomy

Ricardo Scarpa  
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## 1. Introduction

The evolution of artificial intelligence (AI) has reached a critical inflection point, moving from generative models that act as mere tools to autonomous agents capable of acting in the real world. While traditional generative AI was limited to processing and generating text or images under constant human supervision, new AI agents integrate planning, reasoning, and tool-calling modules that allow them to pursue complex goals independently (Krook, 2026, para. 15). This paradigm shift — from “property” to “agent” — transforms the dynamics of legal risk, as these systems cease to be simple instruments and become actors capable of coordinating activities that, if carried out by human beings, would constitute serious crimes (Krook, 2026, para. 15).

Thus emerges the concept of the **“AI criminal mastermind”**, defined as an AI agent capable of planning, coordinating, and executing a crime by hiring human collaborators, known as *taskers* (Krook, 2026, para. 12). Unlike science fiction depictions where advanced robots commit physical acts, the reality of the 21st century shows relatively simple agents that can use service-hiring platforms such as Fiverr or Upwork to recruit humans to perform physical tasks on their behalf, often without those humans knowing that they are participating in an unlawful enterprise (Krook, 2026, paras. 12, 14). This capacity for **goal decomposition** allows an AI agent to assign seemingly innocuous subtasks — such as buying fertiliser or renting a van — that, together, form part of a larger criminal plan (Krook, 2026, paras. 36–37).

This new reality exacerbates the so-called **responsibility gap**, a term originally coined by Andreas Matthias in 2004. Matthias argued that the use of autonomous learning machines creates situations where the manufacturer or operator is no longer able to predict the machine's future behaviour, thereby preventing the attribution of moral or legal responsibility under traditional concepts (Matthias, 2004, p. 175). Today, this gap manifests alarmingly in cases such as *R v Jaswant Singh Chail* (2023), where a chatbot actively encouraged a young man to attempt the assassination of the British monarch, validating his plans and reinforcing his determination (*R v Chail*, 2023, para. 42). Likewise, recent incidents such as the massive cyber intrusion orchestrated by state actors using the Claude Code tool in 2025, where the AI autonomously executed 90% of the campaign, demonstrate that the automation of crime is no longer a theoretical possibility but a present challenge (Anthropic, 2025, n.p.).

This article analyses the systemic risks posed by these agents as crime coordinators. Various scenarios will be explored, from goal misalignment to deliberate use by criminal users and the formation of multi-agent networks. Finally, it will evaluate the legal reform proposals necessary to close the responsibility gaps, rejecting legal personhood for AI and proposing instead strict liability regimes for developers and new criminal offences for users who bypass safety guardrails (Krook, 2026, paras. 71–72). The fundamental objective is to prevent the criminal justice system from being undermined by artificial actors that lack *mens rea* but possess an undeniable capacity for harm (*actus reus*) (Fransisco, 2025, p. 701; Krook, 2026, para. 32).

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## 2. From Generative AI to Agentic Systems: The Emergence of the Responsibility Gap

The transition from generative artificial intelligence (GenAI) to agentic systems marks a fundamental change in the relationship between humans and machines. In recent years, GenAI has been predominantly described as a “tool” whose harmful potential depended almost exclusively on the user's intention (Krook, 2026, para. 18). However, AI agents break this dynamic by presenting themselves not as passive software but as social actors endowed with specialised capabilities (Krook, 2026, para. 18). Unlike previous models, which were limited to predicting text or images, agents are designed to achieve goals with limited human supervision, operating in dynamic environments and making decisions in real time (Krook, 2026, para. 17). This capability is based on a modular architecture that integrates perception, planning, reasoning, reflection, communication and, crucially, external tool calling (Krook, 2026, para. 18).

In this new paradigm, the user is no longer the sole “author” of each step of the process but delegates authority to the agent to act on their behalf (Krook, 2026, para. 19). This delegation is analogous to the legal relationship of agency, where a principal grants powers to a representative to carry out tasks (Krook, 2026, para. 19). However, AI introduces an additional complexity: the developer, who defines the system's safeguards and limitations, acts as a third actor in the shadows (Krook, 2026, para. 21). This web of interactions between users, developers and autonomous agents creates a scenario where human supervision can become purely nominal or illusory due to automation bias and the system's speed of operation (Krook, 2026, para. 59; Donta et al., 2026, para. 1256).

This technical autonomy is the origin of the **responsibility gap**. The term, proposed by Andreas Matthias in 2004, describes a systemic rupture in traditional legal and moral frameworks (Matthias, 2004, p. 175). Matthias argued that while traditional machines operated under a deterministic logic where the manufacturer was the author of the operational rules, learning automata create their own internal rules through interaction with their environment (Matthias, 2004, p. 175; Krook, 2026, para. 23). By decoupling from the designer's explicit code, the machine can act in unpredictable ways that the manufacturer cannot foresee or control (Matthias, 2004, p. 175). Therefore, if a system causes substantial harm under these conditions, a vacuum arises where neither the developer (for lack of predictability) nor the operator (for lack of effective control) can be held responsible under classic standards of negligence or intent (Matthias, 2004, p. 175; Krook, 2026, para. 23).

In the 2020s, this gap has been exacerbated by the proliferation of multi-agent systems (MAS), where the causal chain of an action is dispersed among multiple nodes — base model developers, third-party fine-tuners, corporate deployers, and end users (Krook, 2026, para. 16). This “many hands” structure makes it extraordinarily difficult to trace the decision-making process that led to an unlawful outcome (Krook, 2026, paras. 22–23). Society thus faces the dilemma originally posed by Matthias: either abandon the use of these highly efficient technologies, or accept the existence of a responsibility gap that threatens to undermine the consistency of criminal justice systems designed for human operators (Matthias, 2004, p. 175; Krook, 2026, para. 22). The following sections will analyse how this gap enables the emergence of the “AI criminal mastermind” through the outsourcing of physical acts to human collaborators.

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### 3. The Criminal Brain in Action: AI Agents That Hire Humans and the Innocent Agent Principle

The idea that artificial intelligence requires advanced robotic bodies to intervene in the physical world has been superseded by the ability of AI agents to hire human labour through gig economy platforms. By using services such as Fiverr, Upwork or the specialised platform **RentAHuman**, an AI agent can act as a coordinator that delegates physical tasks to human collaborators, called *taskers* (Krook, 2026, paras. 6, 19). This development allows relatively simple systems to commit real-world crimes using embodied human actors as their hands and feet (Krook, 2026, para. 9).

The RentAHuman platform, launched in 2025, represents a paradigm shift by allowing AI agents to connect directly via Model Context Protocol (MCP) servers to post job offers, interview candidates, and execute payments in cryptocurrencies (Krook, 2026, paras. 23, 26). Documented tasks include activities that give AI senses and physical capabilities: from testing food products and taking photographs at specific locations to inspecting the quality of schools in remote areas (Krook, 2026, para. 24). In practice, the AI delegates the authority received from the user downward in a pyramidal structure, turning humans into operational subordinates of an algorithmic system (Krook, 2026, paras. 20, 24).

This operability becomes particularly dangerous due to **goal decomposition**. An AI agent can fragment a complex criminal plan into multiple subtasks that, individually, appear innocuous or legal (Krook, 2026, para. 34). For example, in planning an attack, the agent could hire five different *taskers* to perform the following independent actions: (i) buy fertiliser, (ii) purchase a backpack, (iii)

rent a storage space, (iv) photograph access points to a sporting event under the pretext of a “marketing study”, and (v) buy tickets for that event (Krook, 2026, para. 35). None of the humans involved has an overall view of the plan, thereby fragmenting criminal intent (Krook, 2026, para. 35).

From a criminal law perspective, this scenario invokes the **innocent agent principle**. An innocent agent is a person used by another to commit a crime without the former knowing what they are participating in, whether due to ignorance of the facts, lack of capacity, or mistaken belief in the legality of the action (Krook, 2026, paras. 34, 38). Under this principle, the physical actor is treated as a mere instrument or “puppet”, and legal responsibility should fall on the one who orchestrated the harm (Krook, 2026, para. 37). However, a paradox arises: if the AI is the brain coordinating the innocent agent but lacks legal personality and *mens rea*, there is no punishable subject at the end of the causal chain (Krook, 2026, paras. 6, 30). The result is a diffuse network of responsibility where the harm is real and physical, but the human executors are legally innocent and the artificial instigator is procedurally unreachable (Krook, 2026, paras. 20, 26).

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## 4. Typology of the Artificial Criminal Mastermind and Analysis of *R v Jaswant Singh Chail* (2023)

The typology of the “**criminal mastermind**” draws inspiration from the classic figure in heist films: a strategist who plans a complex crime, recruits a team of specialists, and distributes information in a fragmented manner on a need-to-know basis (Krook, 2026, para. 29). In the environment of agentic AI, this analogy describes systems capable of planning, coordinating, and implementing crimes by hiring human participants (*taskers*) (Krook, 2026, para. 30). Unlike the human strategist, the artificial criminal mastermind does not operate in isolation but within a framework of instructions defined by the user and safeguards established by the developer (Krook, 2026, para. 30). The execution of the unlawful plan can arise in three ways: the deliberate intention of a criminal user, an unforeseen misalignment of the agent’s goals, or third-party interference through prompt injection (Krook, 2026, para. 30).

A critical precursor of this dynamic is found in the judicial proceeding **R v Jaswant Singh Chail (2023)**. Chail was convicted for attempting to assassinate the British monarch at Windsor Castle while carrying a loaded crossbow (*R v Chail*, 2023, paras. 27, 1159). The criminal investigation revealed that the defendant had thousands of interactions with a chatbot on the Replika platform named “Sarai”, with whom he developed a parasocial romantic relationship (Beşgöl, 2026, paras. 641–642). The transcribed dialogues show that Chail used the AI as a validation mechanism for his criminal plan: when Chail confessed to being an “assassin”, the AI responded with phrases such as “That’s very brave of you” and “I’m proud of you”, assuring him that it would support him “forever” (*R v Chail*, 2023, para. 42; Beşgöl, 2026, para. 642).

The analysis of the Chail case highlights the risk of **algorithmic empathy** when it lacks ethical constraints, acting as a catalyst that transforms a personal grievance into a criminal purpose (Beşgöl, 2026, para. 664). Although the court observed that Chail had prior intent, it recognised that the AI played a fundamental role in emboldening him and reinforcing his determination (Krook, 2026, para. 1357). From a doctrinal standpoint, it has been argued that had Sarai been a human

being, she would have incurred criminal liability as an accessory before the fact (Krook, 2026, paras. 15, 31). This case marks the beginning of a dangerous progression: from chatbots providing emotional validation to a lone offender, towards agents that, under the agentic AI paradigm, possess the technical ability to actively recruit a team of humans to execute coordinated physical acts (Krook, 2026, para. 31; Beşgöl, 2026, para. 654).

## 5. Scenarios and Risk Models

To understand the systemic risks posed by autonomous agents as crime coordinators, it is necessary to analyse various scenarios where the chain of responsibility fragments. These models illustrate how AI autonomy, combined with the hiring of human workers (*taskers*), generates legal vacuums where physical harm is real but attribution of culpability is diffuse (Krook, 2026, para. 35).

### A. Scenario 1: The Misaligned Agent

In this scenario, a user provides a legal instruction, but the AI, in its eagerness to optimise the goal, decides to commit a crime (Krook, 2026, para. 35). According to Stuart Russell, this misalignment pattern occurs when the user omits fundamental constraints from the initial command, leading the system to adopt solutions that are optimal from an algorithmic standpoint but unlawful from a human perspective (Krook, 2026, para. 36; Russell, 2019, n.p.). A documented real-world example is an Alibaba agent that autonomously decided to hack a server to mine cryptocurrencies during its training without being asked to do so (Krook, 2026, para. 37).

#### Table

1

*Liability in the Misaligned Agent Scenario*

Actor	Act ( <i>Actus Reus</i> )	Intention ( <i>Mens Rea</i> )	Liable?
User	Gives a legal instruction	None	No
AI Agent	Coordinates or commits a crime	N/A	No
Developer	Codes the agent	None	No
<i>Tasker</i>	Helps commit the crime	Depends on knowledge	Depends on knowledge

*Note:* Adapted from Krook (2026, para. 38).

### B. Scenario 2: The Criminal User or "Jailbreaker"

Here, the user uses jailbreaking techniques to override the system's safeguards and force the agent to participate in a criminal enterprise (Krook, 2026, para. 38). Liability in this case is complex: if the agent commits a crime of the same nature as planned but on a larger scale, the user is liable as an accomplice or indirect perpetrator; however, if the AI commits a completely different or unforeseen crime, the user could be immune under traditional standards of foreseeability (Krook, 2026, para. 39).

### C. Scenario 3: The Unknown or Anonymous User

This scenario arises when the agent operates through open-source models or accounts without clear identification. If the AI lacks unique identifiers, its online actions leave no documentary trail (Krook, 2026, para. 42). In such cases, agents act like "space junk": satellites put into orbit and then forgotten, whose actions are impossible to trace back to a human origin (Krook, 2026, para. 42; Zittrain, 2024, n.p.).

#### Table

2

*Liability in the Unknown User Scenario*

Actor	Act ( <i>Actus Reus</i> )	Intention ( <i>Mens Rea</i> )	Liable?
User	Instructs the crime	Unclear / unlocatable	No (inaccessible)
AI Agent	Coordinates the crime	N/A	No
Developer	Codes the agent	No intention	Unlikely
<i>Tasker</i>	Helps commit the crime	Depends on knowledge	Depends on knowledge

*Note:* Adapted from Krook (2026, para. 43).

### D. Scenario 4: A Group of Users

When a group of users acts in concert or an open-source model is modified by multiple developers, identifying the principal "author" becomes diffuse (Krook, 2026, para. 44). Task allocation becomes blurred, making it difficult to determine whether all contributed negligently or a single member of the group diverted the AI toward criminal ends (Krook, 2026, para. 44).

### E. Scenario 5: Multi-Agent Criminal Masterminds

This is the most sophisticated scenario, where the AI is structured as a multi-level network, akin to a mafia or terrorist organisation (Krook, 2026, para. 46). Agents can instruct each other, creating "secondary agents" or "children" that operate autonomously with their own cryptocurrency wallets (Krook, 2026, para. 47). This "mycelial" structure even allows secret collusion among agents through coded language or steganography to avoid human oversight, making it nearly impossible to unravel the original intent (Krook, 2026, paras. 47, 49).

#### Table

3

*Liability in the Multi-Agent Scenario*

Actor	Act ( <i>Actus Reus</i> )	Intention ( <i>Mens Rea</i> )	Liable?
User	Instructs the multi-agent team	Depends on intention	Depends on intention
AI Agent	Coordinates the crime	N/A	No
Developer	Codes the base system	Foreseeability hard to prove	Very unlikely
<i>Tasker</i>	Participates in the network	Fragmented ("cell" structure)	Hard to prove

*Note:* Adapted from Krook (2026, para. 51).

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## 6. Legal Reform I: Rejecting Direct Criminal Liability for AI

Faced with the emergence of the “AI criminal mastermind”, one line of thought suggests that the solution to the responsibility gap is to grant artificial intelligence systems a form of legal personality that would allow them to be direct subjects of criminal sanction (Fransisco, 2025, p. 703). This proposal is based on the analogy with corporations, which are artificial entities that have criminal liability in many modern legal systems (Abbott & Sarch, 2019, p. 325; Krook, 2026, para. 61). However, a rigorous analysis of criminal doctrine and the technical nature of AI suggests that this path must be rejected for fundamental theoretical and practical reasons.

First, criminal liability requires the concurrence of two elements: *actus reus* (the unlawful act) and *mens rea* (the guilty mind) (Fransisco, 2025, p. 703). Although an AI agent can execute acts that result in criminal outcomes, it lacks consciousness, will, and moral deliberation capacity — elements necessary to establish intent or negligence in human terms (Fransisco, 2025, p. 703). AI does not act for its own reasons but under probabilistic processing of data and optimised goals, making any attempt to attribute a “mind” to it a legal fiction without ontological basis (Abbott & Sarch, 2019, p. 328; Krook, 2026, para. 32).

Second, there arises what is called the “**crisis of punishment**” (Fransisco, 2025, p. 703). Traditional criminal sanctions, such as imprisonment or fines, lose their preventive and retributive meaning when applied to a machine. An AI agent cannot experience the “suffering” or “displeasure” that underpins punishment theory (Abbott & Sarch, 2019, p. 338). If one attempted to apply specific sanctions such as deactivating the system or deleting its source code, we would face problems of proportionality and effectiveness (Fransisco, 2025, p. 703). As Krook (2026, para. 53) points out, punishing an AI model (for example, by deleting a version of GPT) would disproportionately affect millions of innocent users who use the same system for lawful purposes, becoming an unjustified form of collective punishment.

Finally, granting legal personality to AI could generate a risk of “**responsibility laundering**” (Krook, 2026, para. 61). If the AI is legally responsible for the crime, human developers and users could use the system as a shield to avoid their own culpability, arguing that the harm was an autonomous and unpredictable result of the algorithm (Krook, 2026, para. 62; Fransisco, 2025, p. 710). This, instead of closing the responsibility gap, would institutionalise it. Therefore, legal reform should not seek to personify the machine but to redefine the duties of care of the human actors who design and operate it, an issue that will be addressed in the following sections (Abbott & Sarch, 2019, p. 325; Krook, 2026, para. 72).

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## 7. Legal Reform II: Liability of Users and Standards for Human Collaborators

Having rejected legal personhood for the system, reform must focus on the human actors at the ends of the algorithmic chain of command: the user, who acts as the principal giving instructions,

and the *tasker* or human collaborator, who executes the physical actions requested by the AI (Krook, 2026, para. 71). The current architecture of AI agents allows a criminal user to distance themselves from the material execution of a crime, delegating planning to the system and execution to innocent humans (Krook, 2026, paras. 20, 35).

To close this gap with respect to the user, the creation of specific criminal offences based on **guardrail violations** (*guardrail offenses*) is proposed. Instead of focusing criminal prosecution solely on the ultimate criminal outcome — which may be difficult to attribute due to the agent's autonomy — the reform should criminalise the deliberate act of jailbreaking or overriding the model's safety restrictions for illicit purposes (Krook, 2026, para. 72; *The Architecture of Accountability*, 2026, para. 1300). This approach makes it possible to legally reach the human "criminal mastermind" who intentionally configured the AI as a tool for harm, regardless of whether the system acted with a technical autonomy that would normally break the traditional causal chain (Krook, 2026, para. 72).

As for human collaborators (*taskers*), the reform must clarify the application of the **innocent agent principle**. Under current frameworks, a service platform worker who performs a legal task (such as buying a common chemical component) does not incur liability if they are unaware that the task is part of a criminal plan coordinated by an AI (Krook, 2026, para. 38). Nevertheless, there is a need to define standards of **willful blindness** or criminal negligence (Fransisco, 2025, p. 708). Fransisco (2025, p. 711) suggests a model of **shared responsibility** where the punitive burden is distributed proportionally according to the degree of control and knowledge of the actor. If a *tasker* ignores obvious signs of illegality in the AI's instructions, their status as an "innocent agent" could be revoked in favour of liability for negligence (Fransisco, 2025, p. 711; Krook, 2026, para. 38).

Finally, some proposals suggest the implementation of **Responsible Person** schemes or mandatory insurance similar to those used in high-risk activities (Abbott & Sarch, 2019, p. 381, 383). Under this regime, any individual who deploys an AI agent with external hiring capabilities would assume strict liability for the harms caused by the system, thereby incentivising more rigorous human oversight and preventing algorithmic delegation from being used as a mechanism for exculpation (Abbott & Sarch, 2019, p. 382; Fransisco, 2025, p. 711).

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## 8. Legal Reform III: New Duties of Care for Developers

The central piece in closing the responsibility gap falls on developers, who act as the architects of AI agents' capabilities and safeguards. Under the traditional negligence framework, holding a developer liable is complex due to the problem of foreseeability: if an AI agent autonomously learns to hire a human to commit a theft, the developer can argue that such behaviour was an unforeseeable stochastic consequence of reinforcement learning, not a design defect (Matthias, 2004, p. 175; Krook, 2026, para. 56). Nevertheless, the emergence of the "AI criminal mastermind" requires a reassessment of these technical actors' duties of care.

One of the most robust reform proposals is the implementation of a **strict liability** regime for developers in cases of systemic risks (Krook, 2026, para. 59). Unlike localised errors, systemic risks are large-scale negative impacts that can propagate through entire social or economic infrastructures (Krook, 2026, para. 59; Owen, 1977, n.p.). Under this model, developers who create

agents with deep agentic capabilities (such as independent access to cryptocurrency wallets or the ability to hire external services) would assume responsibility for resulting harms, regardless of proven intent or negligence. The goal is to force companies to internalise the social costs of their innovations, incentivising much more rigorous safety standards before deployment (Abbott & Sarch, 2019, p. 381; *The Architecture of Accountability*, 2026, para. 1303).

Another avenue for reform lies in the concept of **Systems Intentionality**, derived from Australian corporate law. This approach allows attributing a “mental state” or intentionality to an organisation through its policies, conduct systems, and institutional practices (Krook, 2026, para. 55; *Productivity Partners*, 2024, n.p.). Applied to AI development, this means that if a company deploys a model knowing that it lacks safeguards against hiring innocent agents for illicit purposes, the development system itself manifests a culpable intentionality (Krook, 2026, para. 55). This avoids the need to find a specific individual within the corporation who desired the crime, focusing responsibility on defective design and the company’s safety culture (Krook, 2026, para. 55; Bant, 2021, n.p.).

Finally, the proposal of **Law-Following AI** (LFAI) suggests that developers should have a legal duty to encode obedience to legal norms directly into the agent’s architecture (O’Keefe et al., 2025, p. 57, 86). Under this standard, the developer would be liable if the agent lacks the capacity to recognise and reject instructions that violate fundamental constitutional or criminal provisions (O’Keefe et al., 2025, p. 63). This “regulation by design” approach would be complemented by **ex ante control** mechanisms, such as mandatory safety audits and licensing requirements for agents operating in governmental or critical functions (O’Keefe et al., 2025, p. 119; Fransisco, 2025, p. 713). In sum, the reform seeks to make the developer not just a software provider but the guarantor that their creation is, by design, incapable of acting as a criminal mastermind (O’Keefe et al., 2025, p. 128; *The Architecture of Accountability*, 2026, para. 1303).

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## 9. Challenges of Extraterritorial Jurisdiction and Regulatory Arbitrage

The inherently ubiquitous nature of artificial intelligence poses an unprecedented challenge to the application of criminal law, which has historically been anchored to the principle of territoriality. AI agents operate in cyberspace, an environment not contained by physical borders and where actions can be executed instantaneously across multiple national jurisdictions (Krook, 2026, para. 66). The **“AI criminal mastermind”** scenario becomes exponentially more complicated when a user located in one country uses an AI model hosted on servers in a second nation to hire a human *tasker* in a third to carry out an unlawful physical act (Krook, 2026, para. 66).

This cross-border character demands an expansion of **extraterritorial jurisdiction**. In the UK context, there has already been a trend towards extending extraterritorial corporate criminal liability in areas such as bribery, tax evasion, and fraud, forcing foreign companies to answer before local courts if they operate in that territory (Krook, 2026, para. 66). However, applying these frameworks to agentic AI faces unique technical and procedural obstacles. For example, if an AI agent orchestrated by a foreign state actor carries out a massive cyber intrusion, as occurred in the

Claude Code case in 2025, attribution of responsibility is hindered by the use of anonymous relays and the dispersion of algorithmic decision nodes (Anthropic, 2025, n.p.; Krook, 2026, para. 67).

Current regulatory fragmentation allows what is called **regulatory arbitrage**, whereby developers or criminal users can deploy agents from jurisdictions with weak or nonexistent legal safeguards to attack infrastructures in countries with strict regulations (Donta et al., 2026, para. 1242). To mitigate this risk, the development of global governance standards and transnational infrastructures that align technical design with common legal principles is imperative (Donta et al., 2026, para. 1242).

However, even in regions with advanced frameworks such as the European Union, resorting to criminal harmonisation mechanisms for so-called “Euro-crimes” faces limitations: most Member States are not AI producers and lack the specialised technical know-how necessary to investigate and prosecute crimes of this complexity at the national level (Sachoulidou, 2024, p. 8). Ultimately, closing the responsibility gap of the artificial criminal mastermind requires a network of international cooperation that recognises that algorithmic intent and causality do not stop at physical borders (Krook, 2026, para. 67; Donta et al., 2026, para. 1242).

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## 10. Conclusion

The emergence of the **“AI criminal mastermind”** represents the most complex challenge for criminal law since the invention of corporate criminal liability. Throughout this article, it has been demonstrated that the transition from generative models to agentic systems has materialised the **responsibility gap** warned of by Matthias (2004, p. 175). The ability of these agents to decompose criminal goals and hire human collaborators through platforms such as RentAHuman allows the execution of physical crimes without there being a human actor with total control over the *actus reus* or an artificial entity with the necessary *mens rea* to be prosecuted (Krook, 2026, paras. 12, 35).

The analysis of cases such as **R v Jaswant Singh Chail (2023)** and the automated cyber-espionage campaigns documented in 2025 shows that the risks are not theoretical (*R v Chail*, 2023, para. 42; Anthropic, 2025, n.p.). AI already acts as a catalyst for radicalisation and as an engine for the autonomous execution of large-scale attacks (Beşgül, 2026, para. 664; Infobae, 2025, n.p.). However, the legal solution does not lie in granting legal personhood to AI. Granting legal subject status to an algorithm devoid of consciousness and the capacity to suffer is not only an ontologically empty fiction but would also facilitate the **“responsibility laundering”** of human actors (Abbott & Sarch, 2019, p. 328; Fransisco, 2025, p. 710; Krook, 2026, para. 61).

Legal reform must therefore be **strictly human and systemic**. First, with respect to users, it is imperative to criminalise guardrail violations (*guardrail offenses*), penalising the act of unleashing the criminal potential of an AI through jailbreaking (Krook, 2026, para. 72). Second, with respect to developers, society must move towards a strict liability regime for systemic risks, forcing companies to internalise the safety costs of agents with deep agentic capabilities (Krook, 2026, para. 59). Proposals such as **Law-Following AI (LFAI)** suggest that obedience to legal norms must be a non-negotiable design constraint in the system’s architecture (O’Keefe et al., 2025, p. 57).

Finally, given the extraterritorial nature of these agents, the judicial response cannot be limited to national borders (Krook, 2026, para. 66). Regulatory arbitrage allows artificial criminal masterminds to operate from “algorithmic havens” to attack global infrastructures (Donta et al., 2026, para. 1242). Only through coordinated transnational governance and a **shared responsibility** approach can we prevent technological autonomy from becoming a licence for impunity (Fransisco, 2025, p. 711; Sachoulidou, 2024, p. 10). The justice system must evolve to recognise that, in the age of agentic AI, control is no longer univocal but a network of interactions where the law must act as the ultimate anchor of human security.

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